Mass Storage Structure

*Throughout the course we will use overheads that were adapted from those distributed from the textbook website. Slides are from the book authors, modified and selected by Jean Mayo, Shuai Wang and C-K Shene.

> You don't understand anything until you learn it more than one way.

> > Marvin Minsky

Spring 2019

Disk Structure

- Three elements: cylinder, track and sector/block.
 Three types of latency (*i.e.*, delay)
 - Positional or seek delay mechanical and slowest
 - track t - spindle **Rotational delay Transfer** delay arm assembly sector s. read-write cylinder $c \rightarrow$ head platter arm rotation

Computing Disk Latency

- **Track size:** 32K = 32,768 bytes
- **Rotation Time: 16.67 msec (millisecond)**
- Average seek time: 30 msec
- **What is the average time to transfer** *k* bytes?

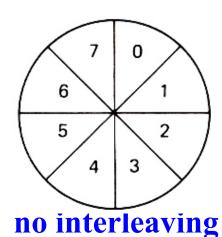
Average read time = 30 + 16.67/2 + (*k*/32K)×16.67

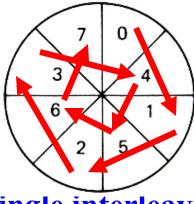
average time to move from track to track

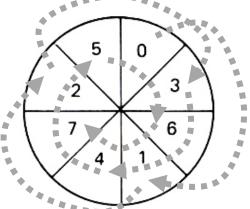
on average, wait a half turn

this is the "length" the disk head must pass to complete a transfer

Disk Block Interleaving

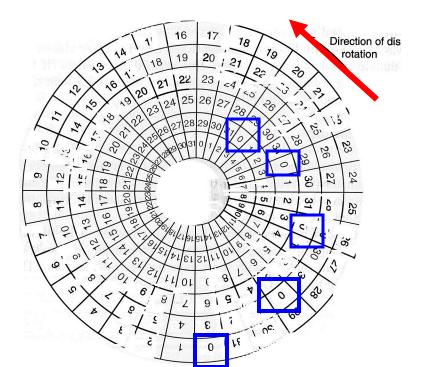






single interleaving d

double interleaving



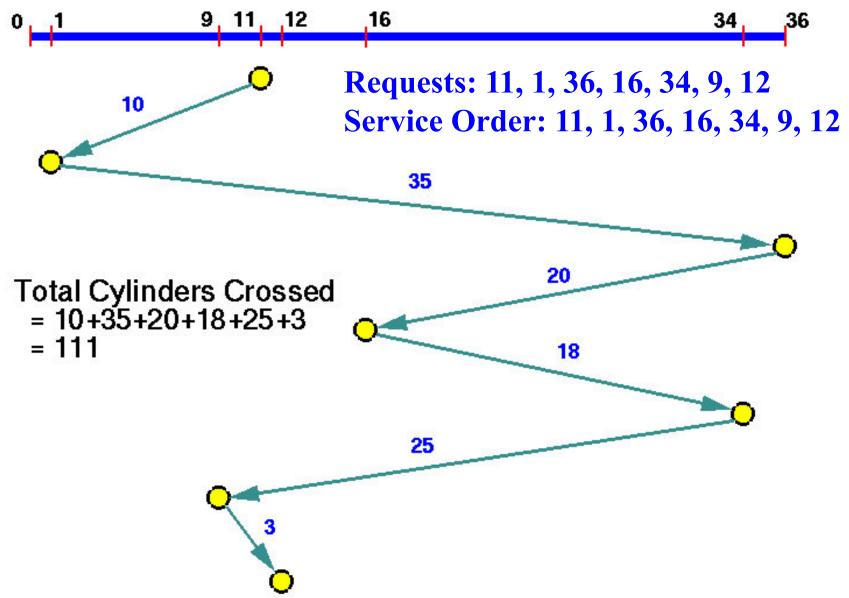
Cylinder Skew

The position of sector/block 0 on each track is offset from the previous one, providing sufficient time for moving the disk head from track to track.

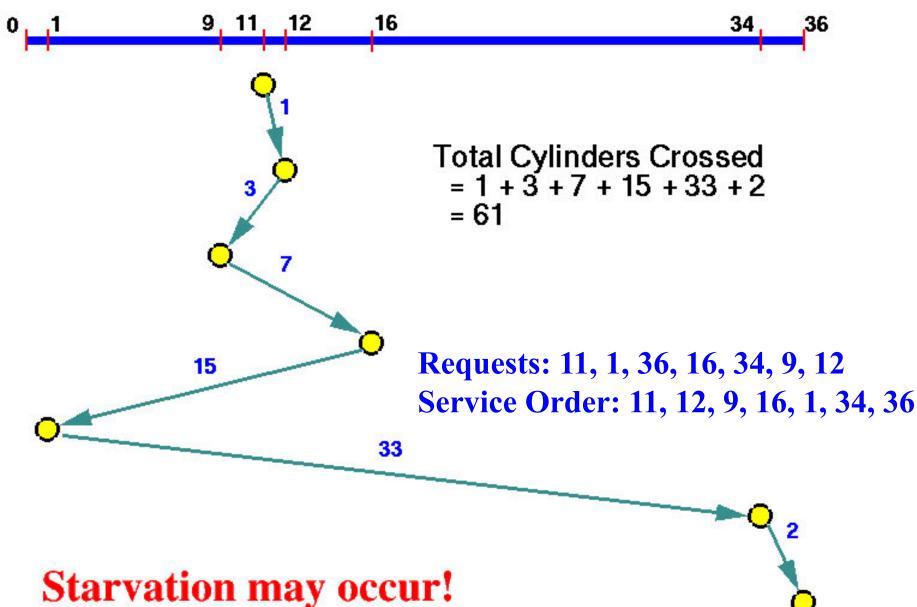
Disk Scheduling

- Since seeking is time consuming, disk scheduling algorithms try to minimize this latency.
- **The following algorithms will be discussed:**
 - >First-come, first served (FCFS)
 - >Shortest-seek-time-first (SSTF)
 - **SCAN and C-SCAN**
 - **COOK and C-LOOK**
- Since seeking only involves cylinders, the input to these algorithms are cylinder numbers.

First-Come, First-Served



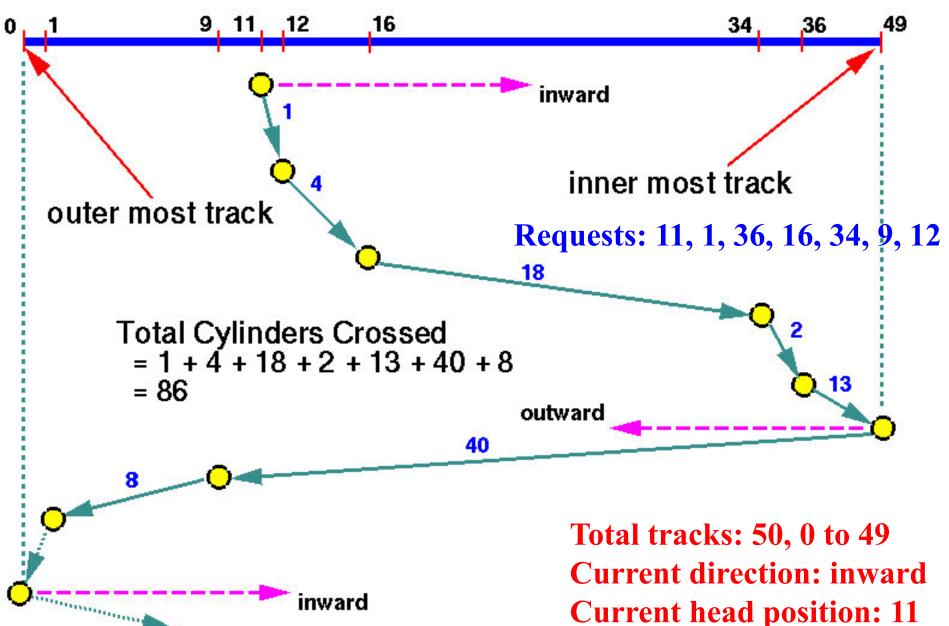
Shortest-Seek-Time-First



SCAN Scheduling: 1/2

- This algorithm requires one more piece of information: the disk head movement direction, *inward* or *outward*.
- **The disk head starts at one end, and move toward the other in the** *current* **direction.**
- At the other end, the direction is *reversed* and service continues.
- Some authors refer to the SCAN algorithm as the *elevator* algorithm. However, to some others the elevator algorithm means the LOOK algorithm.

SCAN Scheduling: 2/2

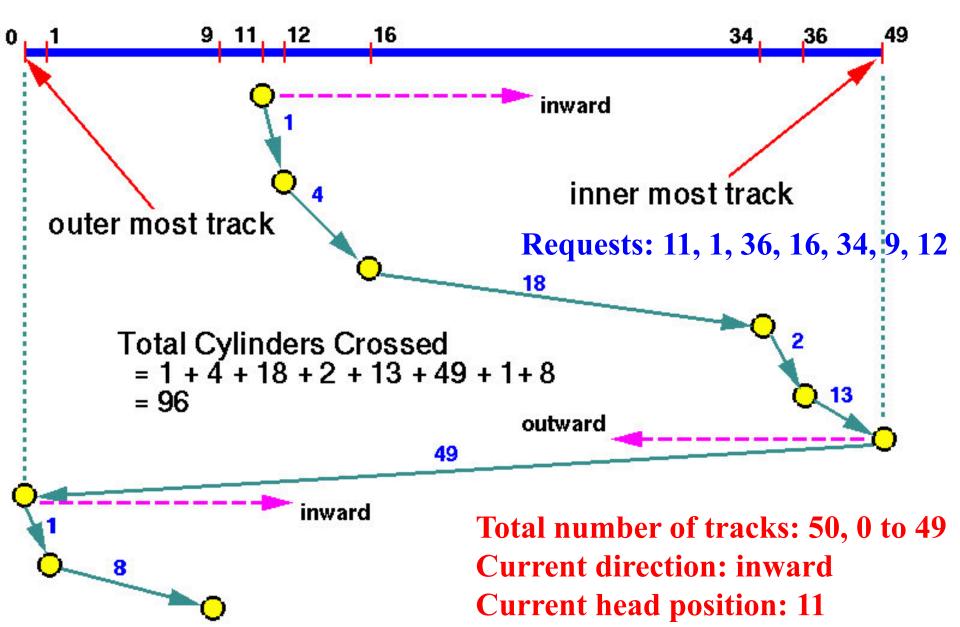


C-SCAN Scheduling: 1/2

C-SCAN is a variation of **SCAN**.

- ❑ When the disk head reaches one end, move it back to the other end. Thus, this is simply a wrap-around (*i.e.*, circular).
- Why is this wrap-around reasonable? As the disk head moves in one direction, new requests may arrive at the other end and requests at the same end may have already been served. Thus, warp-around is sort-of FIFO!
- **The C in C-SCAN means circular.**

C-SCAN Scheduling: 2/2

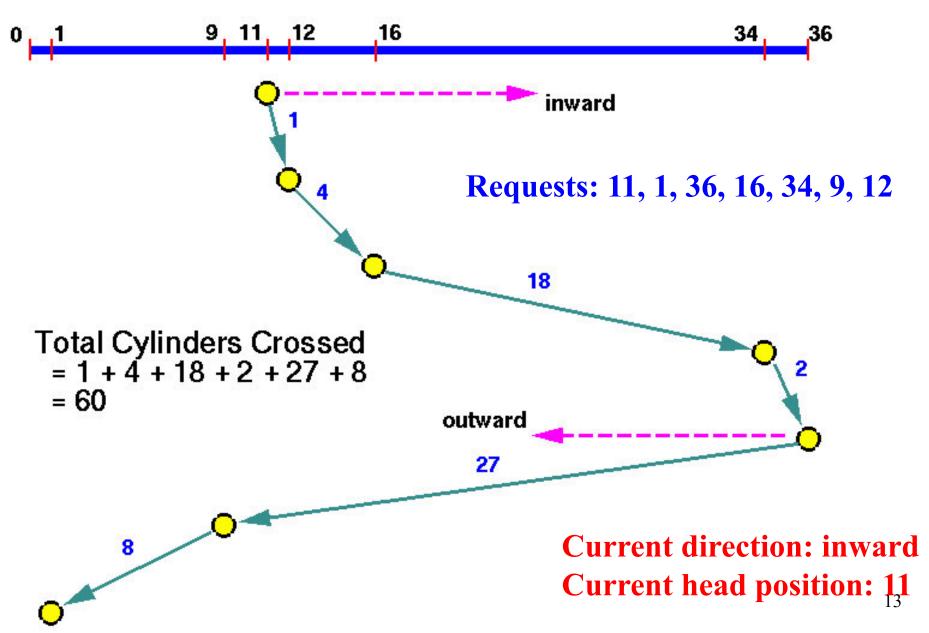


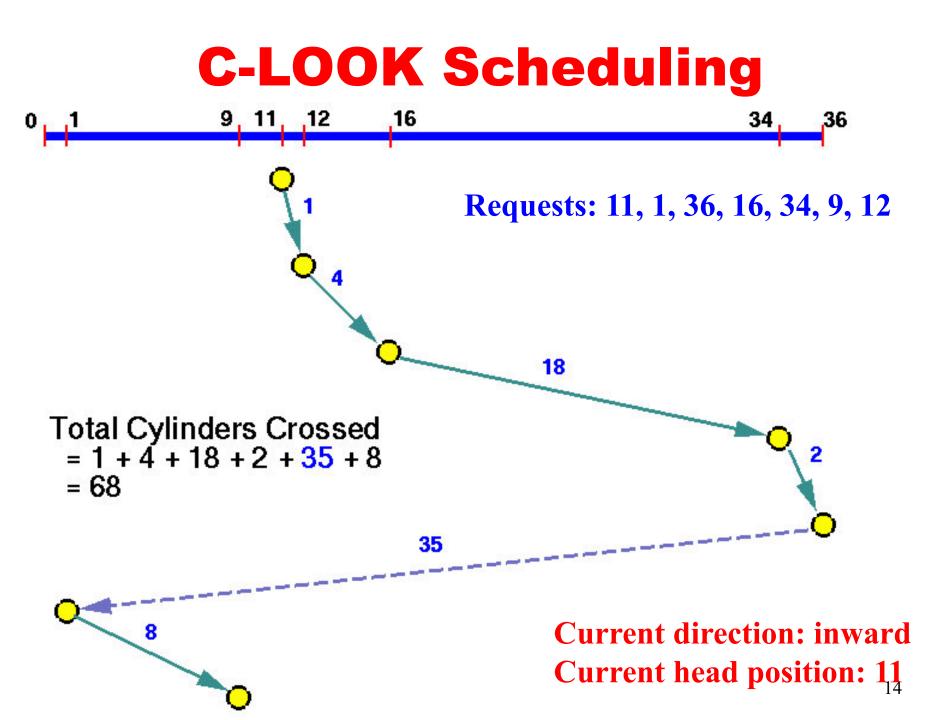
LOOK Scheduling: 1/2

- **With SCAN and C-SCAN, the disk head moves across the full width of the disk.**
- This is very time consuming. In practice, SCAN and C-SCAN are not implemented this way.
- **LOOK:** It is a variation of SCAN. The disk head goes as far as the last request and reverses its direction.

C-LOOK: It is similar to **C-SCAN**. The disk head also goes as far as the last request and reverses its direction.

LOOK Scheduling: 2/2

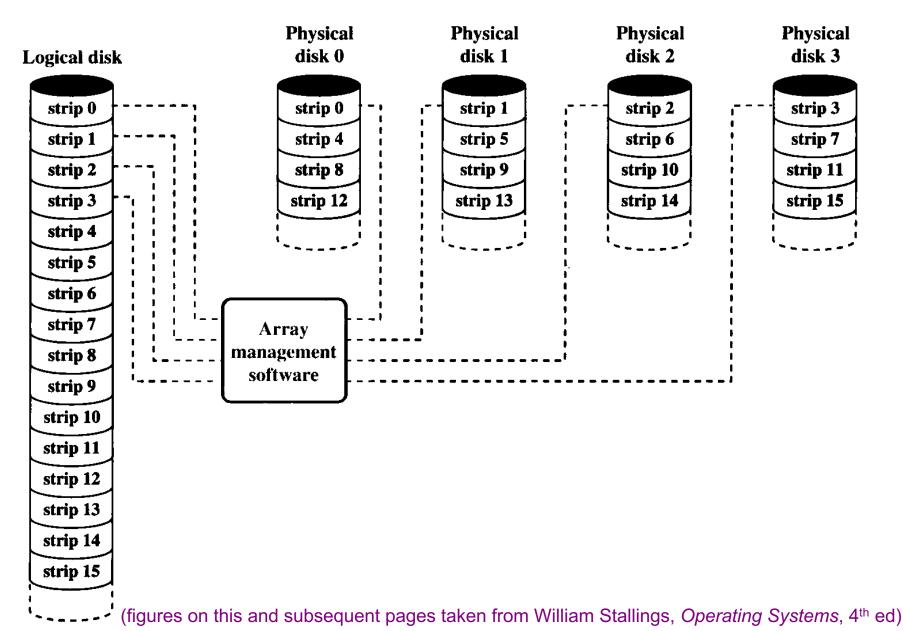




RAID Structure: 1/2

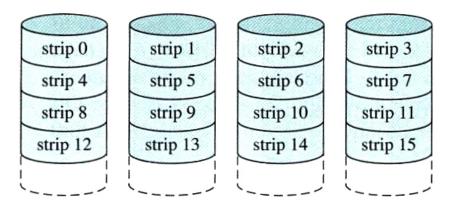
- **RAID:** Redundant Arrays of Inexpensive Disks.
- **RAID** is a set of physical drives viewed by the operating system as a single logical drive.
- **Data are distributed across the physical drivers of an array.**
- Redundant disk capacity is used to store parity information, which guarantees data recoverability is case of disk failure.
- **RAID** has 6 levels, each of which is not necessary an extension of the other.

RAID Structure: 2/2



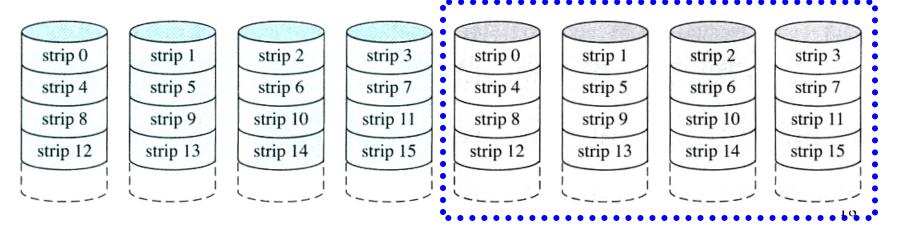
RAID Level 0

- The virtual single disk simulated by RAID is divided up into strips of k sectors each.
- Consecutive strips are written over the drivers in a round-robin fashion. There is no redundancy.
- □ If a single I/O request consists of multiple contiguous strips, then multiple strips can be handled in parallel.



RAID Level 1: Mirror

- Each logical strip is mapped to two separate physical drives so that every drive in the array has a mirror drive that contains the same data.
- **Recovery from a disk failure is simple due to redundancy.**
- A write request involves two parallel disk writes.
 Problem: Cost is high (doubled)! mirror disks

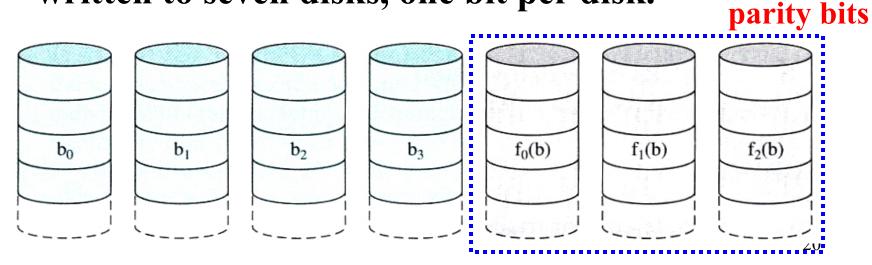


Parallel Access

- RAID Levels 2 and 3 require the use of *parallel access technique*. In a parallel access array, all member disks participate in the execution of every I/O and the spindles of the individual drives are synchronized so that each disk head is at the same position on each disk at any given time.
- **Data strips are very small, usually a single byte or word.**

RAID Level 2: 1/2

- An error-correcting code is calculated across corresponding bits on each data and the bits of code are stored in the corresponding bit positions on disks.
- **Example:** A 8-bit byte is divided into two 4-bit nibbles. A 3-bit Hamming code is added to form a 7-bit word. This 7-bit Hamming coded word is written to seven disks, one bit per disk.

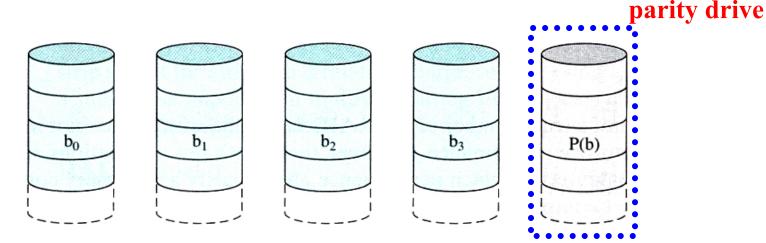


RAID Level 2: 2/2

- **Cost is high, although the number of bits needed is less than that of RAID 1 (mirror).**
- **The number of redundant disks is** $O(\log_2 n)$, where *n* is the number of data disks.
- On a single read, all disks are accessed at the same time. The requested data and the associated errorcorrecting code are delivered to the controller. If there is an error, the controller reconstructs the data bytes using the error-correcting code. Thus, read access is not slowed.
- **RAID 2** would only be an effective choice in an environment in which many disk errors occur.

RAID Level 3: 1/2

- **RAID 3** is a simplified version of to RAID 2. It only needs one redundant drive.
- A single parity bit is computed for each data word and written to a parity drive.
- **Example:** The parity bit of bits 1-4 is written to the same position on the parity drive.

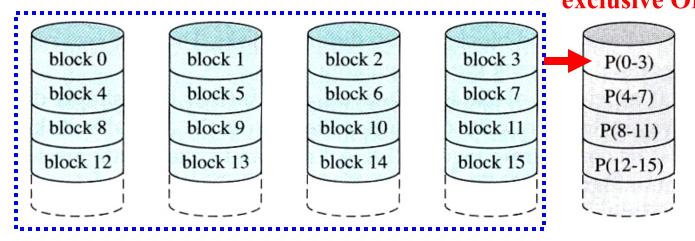


RAID Level 3: 2/2

- ☐ If one failing drive is known, the parity bit can be used to reconstruct the data word.
- Because data are striped in very small strips, RAID 3 can achieve very high data transfer rates.
- Any I/O request involves the parallel transfer of data from all of the data disks. However, only one I/O request can be executed at a time.

RAID Level 4: 1/2

- RAID 4 and RAID 5 work with strips rather than individual data words, and do not require synchronized drives.
- **The parity of all strips on the same "row" is written on an parity drive.**
- **Example:** strips 0, 1, 2 and 3 are exclusive-Ored, resulting in a parity strip.



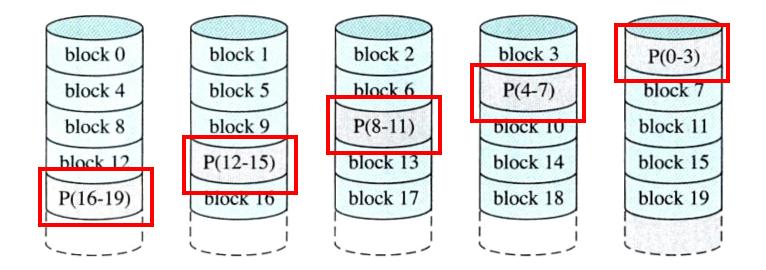
RAID Level 4: 2/2

- □ If a drive fails, the lost bytes can be reconstructed from the parity drive.
- □ If a sector fails, it is necessary to read *all* drives, including the parity drive, to recover.
- **The load of the parity drive is very heavy.**

RAID Level 5

To avoid bottleneck of the parity drive of RAID 4, the parity strips can be distributed uniformly over all drives in a round-robin fashion.

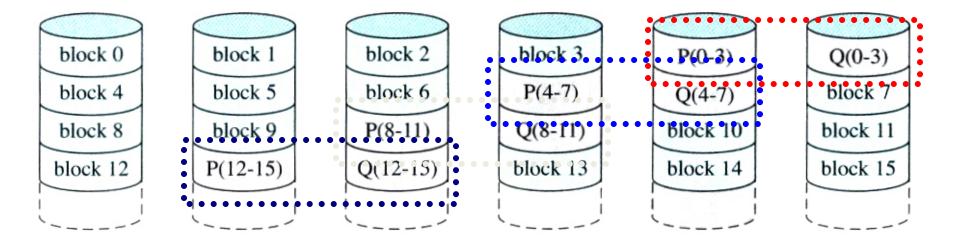
However, data recovery from a disk crash is more complex.



RAID Level 6

RAID has two different parity calculations (*i.e.*, dual redundancy), which are stored in separate blocks on different disks.

Thus, a RAID 6 array whose user data requires N disks would need N+2 disks.



The End