

# Basic Signal Programming

*Adding manpower to a late software project, makes it later.*

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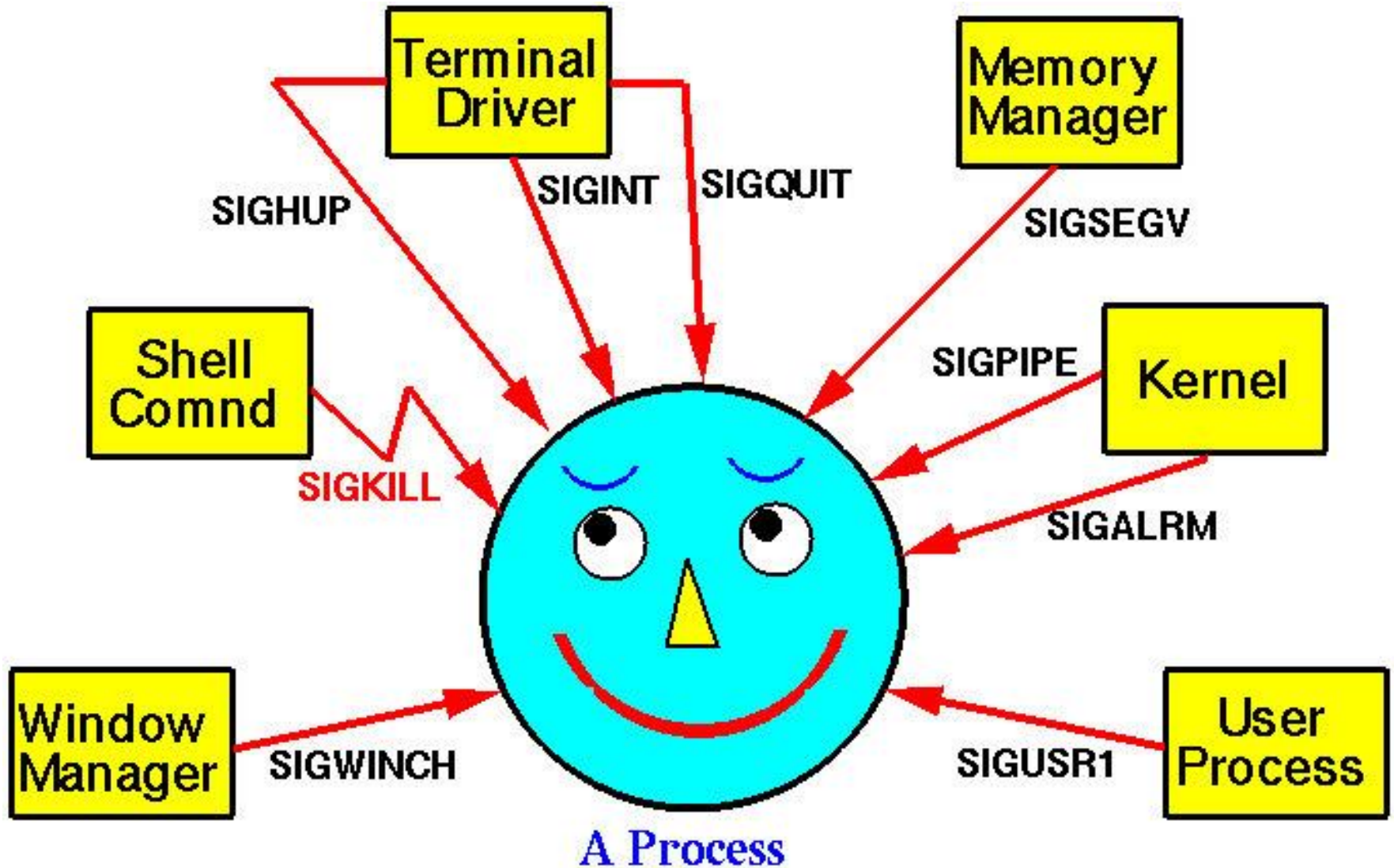
# ***What is a signal?***

- Signals are generated when an event occurs that requires attention. It can be considered as a software version of an interrupt.
- **Signal Sources:**
  - ❖ **Hardware** - division by zero
  - ❖ **Kernel** – notifying an I/O device for which a process has been waiting is available
  - ❖ **Other Processes** – a child notifies its parent that it has terminated
  - ❖ **User** – key press (*i.e.*, Ctrl-C)

# ***What signals are available?***

- ❑ Signal names are defined in `signal.h`
- ❑ The following are Unix examples:
  - ❖ `SIGALRM` – alarm clock
  - ❖ `SIGBUS` – bus error
  - ❖ `SIGFPE` – floating point arithmetic exception
  - ❖ `SIGINT` – interrupt (*i.e.*, `Ctrl-C`)
  - ❖ `SIGQUIT` – quit (*i.e.*, `Ctrl-\`)
  - ❖ `SIGTERM` – process terminated
  - ❖ `SIGUSR1` and `SIGUSR2` – user defined signals
- ❑ You can ignore *some* signals
- ❑ You can also catch and handle some signals.

# Signal Sources



# **Function** signal ()

```
void (*signal(int, void (*)(int))) (int);
```



- **signal ()** is a function that accepts *two* arguments and returns a pointer to a function that takes one argument, the signal handler, and returns nothing. If the call fails, it returns `SIG_ERR`.
- The arguments are
  - ❖ The first is an integer (*i.e.*, `int`), a *signal name*.
  - ❖ The second is a **function** that accepts an `int` argument and returns nothing, the *signal handler*.
  - ❖ If you want to ignore a signal, use `SIG_IGN` as the second argument.
  - ❖ If you want to use the default way to handle a signal, use `SIG_DFL` as the second argument.

# ***Examples***

- ❑ **The following ignores signal SIGINT**

```
signal(SIGINT, SIG_IGN);
```

- ❑ **The following uses the default way to handle SIGALRM**

```
signal(SIGALRM, SIG_DFL);
```

- ❑ **The following installs function INThandler() as the signal handler for signal SIGINT**

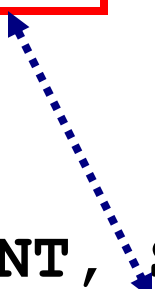
```
signal(SIGINT, INThandler);
```

# ***Install a Signal Handler: 1/2***

```
#include <stdio.h>
#include <signal.h>
```

```
void INThandler(int);
```

```
void main(void)
{
    if (signal(SIGINT, SIG_IGN) != SIG_IGN)
        signal(SIGINT, INThandler);
    while (1)
        pause();
}
```



# ***Install a Signal Handler: 2/2***

```
void INThandler(int sig)
{
    char c;
    signal(sig, SIG_IGN);
    printf("Ouch, did you hit Ctrl-C?\n",
           "Do you really want to quit [y/n]?");
    c = getchar();
    if (c == 'y' || c == 'Y')
        exit(0);
    else
        signal(SIGINT, INThandler);
}
```

*ignore the signal first*

*reinstall the signal handler*



# ***Here is the procedure***

- 1.** Prepare a function that accepts an integer, a **signal name**, to be a signal handler.
- 2.** Call `signal()` with a signal name as the first argument and the signal handler as the second.
- 3.** When the signal you want to handle occurs, ***your*** signal handler is called (by the system) with the argument the signal name that just occurred.
- 4.** Two important notes:
  - a.** You might want to **ignore** that signal in your handler
  - b.** Before returning from your signal handler, don't forget to **re-install** it.

# Handling Multiple Signal Types:

## 1/2

- You can install multiple signal handlers:

```
signal (SIGINT,  INThandler) ;  
signal (SIGQUIT, QUIThandler) ;
```

```
void  INThandler(int sig)  
{  
    // SIGINT handler code  
}
```

```
void  QUIThandler(int sig)  
{  
    // SIGQUIT handler code  
}
```

# ***Handling Multiple Signal Types:***

## ***2/2***

- ❑ **Or, you can use one signal handler and install it multiple times**

```
signal(SIGINT, SIGHandler);  
signal(SIGQUIT, SIGHandler);
```

```
void SIGHandler(int sig)  
{  
    switch (sig) {  
        case SIGINT:    // code for SIGINT  
        case SIGQUIT:  // code for SIGQUIT  
        default:       // other signal types  
    }  
}
```

# ***Handling Multiple Signal Types***

## ***Example: 1/4***

```
#include <stdio.h>
#include <stdlib.h>
#include <signal.h>

#define MAX_i      10000
#define MAX_j      20000
#define MAX_SECOND (2)

void INThandler(int) ;
void ALARMhandler(int) ;

int SECOND, i, j;
/* see next page */
```

# Handling Multiple Signal Types

## Example: 2/4

```
void INThandler(int sig)
{
    char c;
    signal(SIGINT, SIG_IGN);
    signal(SIGALRM, SIG_IGN);
    printf("INT handler: i = %d and j = %d\n", i, j);
    printf("INT handler: want to quit [y/n]?");
    c = tolower(getchar());
    if (c == 'y') {
        printf("INT handler: done"); exit(0);
    }
    signal(SIGINT, INThandler);
    signal(SIGALRM, ALARMhandler);
    alarm(SECOND);
} /* see next page */
```

*This is a Unix system call* 13

# Handling Multiple Signal Types

## Example: 3/4

```
void ALARMhandler(int sig)
{
    signal(SIGINT, SIG_IGN);
    signal(SIGALRM, SIG_IGN);
    printf("ALARM handler: alarm signal received\n");
    printf("ALARM handler: i = %d and j = %d\n", i, j);
    alarm(SECOND);
    signal(SIGINT, INThandler);
    signal(SIGALRM, ALARMhandler);
} /* see next page */
```

*set alarm clock to SECOND seconds*

# ***Handling Multiple Signal Types***

## ***Example: 4/4***

```
void main(int argc, char *argv[])
{
    long sum;

    SECOND = abs(atoi(argv[1]));
    signal(SIGINT, INThandler);
    signal(SIGALRM, ALARMhandler);
    alarm(SECOND);
    for (i = 1; i <= MAX_i, i_++) {
        sum = 0;
        for (j = 1; j <= MAX_j; j++)
            sum += j;
    }
    printf("Computation is done.\n\n");
}
```

# Raise a Signal within a Process: 1/2

- Use ANSI C function `raise()` to “raise” a signal

```
int raise(int sig);
```

- `raise()` returns non-zero if unsuccessful.

```
#include <stdio.h>
#include <signal.h>
```

*Check here if it is a SIGUSR1!*



```
long pre_fact, i;
```

```
void SIGhandler(int);
```

```
void SIGhandler(int sig)
```

```
{
```

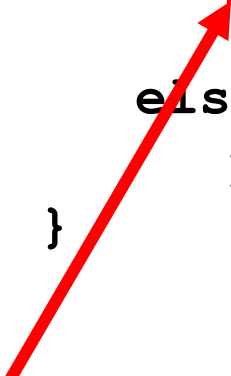
```
    printf("\nReceived a SIGUSR1 signal %ld! = %ld\n",
           i-1, pre_fact);
```

```
} /* see next page */
```



# Raise a Signal within a Process: 2/2

```
void main(void)
{
    long fact;
    signal(SIGUSR1, SIGHandler);
    for (prev_fact=i=1; ; i++, prev_fact = fact) {
        fact = prev_fact * i;
        if (fact < 0)
            raise(SIGUSR1);
        else if (i % 3 == 0)
            printf("    %ld = %ld\n", i, fact);
    }
}
```



*Assuming an integer overflow will wrap around!*

# ***Send a Signal to a Process***

- ❑ Use Unix system call `kill()` to send a signal to another process:

```
int kill(pid_t pid, int sig);
```

- ❑ `kill()` sends the `sig` signal to process with ID `pid`.
- ❑ So, you must find some way to know the process ID of the process a signal is sent to.

# ***Kill Example: process-a 1/3***

```
#include <stdio.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
```

```
void SIGINT_handler(int);
void SIGQUIT_handler(int);
```

```
int    ShmID;
```

```
pid_t  *ShmPTR;
```

```
/* see next page */
```

*used to save shared memory ID*



*my PID will be stored here*



# **Kill Example: process-a 2/3**

```
void main(void)
{
    int    i;
    pid_t  pid = getpid();
    key_t  MyKey;

    signal(SIGINT, SIGINT_handler);
    signal(SIGQUIT, SIGQUIT_handler);
    MyKey = ftok("./", 'a');
    ShmID = shmget(MyKey, sizeof(pid_t), IPC_CREAT|0666);
    ShmPTR = (pid_t *) shmat(shmID, NULL, 0);
    *ShmPTR = pid;
    for (i = 0; ; i++) {
        printf("From process %d: %d\n", pid, i);
        sleep(1);
    }
} /* see next page */
```

# ***Kill Example: process-a 3/3***

```
void SIGINT_handler(int sig)    use Ctrl-C to interrupt
{
    signal(sig, SIG_IGN);
    printf("From SIGINT: got a Ctrl-C signal %d\n", sig);
    signal(sig, SIGINT_handler);
}

void SIGQUIT_handler(int sig)  use Ctrl-\ to kill this program
{
    signal(sig, SIG_IGN);
    printf("From SIGQUIT: got a Ctrl-\ signal %d\n", sig);
    printf("From SIGQUIT: quitting\n");
    shmdt(ShmPTR);
    shmctl(ShmID, IPC_RMID, NULL);
    exit(0);
}
```

# **Kill Example: process-b 1/2**

```
#include <stdio.h>
#include <signal.h>
#include <sys/types.h>
#include <sys/ipc.h>
#include <sys/shm.h>
```

```
Void main(void)
```

```
{
```

```
    pid_t    pid, *ShmPTR;
    key_t    MyKey;
    int      ShmID;
    char     c;
```

```
    MyKey = ftok("./", 'a');
    ShmID = shmget(MyKey, sizeof(pid_t), 0666);
    ShmPTR = (pid_t *) shmat(ShmID, NULL, 0);
```

```
    pid = *ShmPTR;
```

```
    shmdt(ShmPTR); /* see next page */
```

*detach the shared memory  
after taking the pid*



# ***Kill Example: process-b 2/2***

```
while (1) {
    printf("(i for interrupt or k for kill)? ");
    c = getchar();
    if (c == 'i' || c == 'I') {
        kill(pid, SIGINT);
        printf("A SIGKILL signal has been sent\n");
    }
    else if (c == 'k' || c == 'K') {
        printf("About to sent a SIGQUIT signal\n");
        kill(pid, SIGQUIT);
        exit(0);
    }
    else
        printf("Wrong keypress (%c). Try again!\n", c);
}
}
```

*You can kill process-a from within process-b!*

**The End**